

SD9251ET OVERVIEW

The SD9251ET is a dual-channel, 14-bit, analog-to-digital converter (ADC) supporting sampling rates up to 20MSps. The SD9251ET supports an extended temperature range of -55°C to 125°C. The device uses a multistage pipeline architecture to achieve high signal-to-noise ratio (SNR) and linearity, over wide input signal bandwidth. The SD9251ET can be set to operate using either CMOS or LVDS output interface. Programming for configuration and control is accomplished using a 3-wire SPI-compatible serial bus. The digital output data can be programmed to be delivered in offset binary, twos complement format, or gray code.

FEATURES

- Extended temperature range (-55°C to 125°C)
- SNR: 73.1dBFS at $f_{IN} = 30.2\text{MHz}$ and $f_S = 20\text{MSps}$
- SFDR: 91.0dBc at $f_{IN} = 30.2\text{MHz}$ and $f_S = 20\text{MSps}$
- -144.3dBFS/Hz input-noise at $f_{IN} = 30.2\text{MHz}$ and $f_S = 20\text{MSps}$
- 1.8V nominal input
- Typical power consumption: 170mW at 20MSps
- Integer 1-to-8 input clock divider (160MHz maximum input rate)
- Sample rates of up to 20MSps
- 1.8V analog supply voltage
- Up to 3.3V digital I/O supply voltage (CMOS Output)
- LVDS (ANSI-644 levels) outputs
- Internal ADC voltage reference
- ADC clock duty cycle correction
- Serial port control
- Energy saving power-down modes

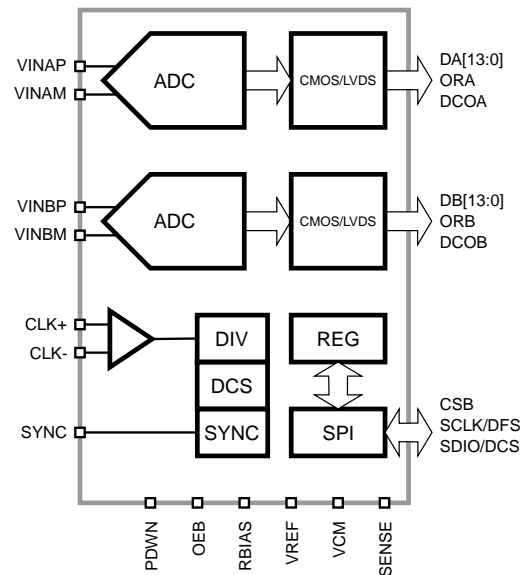


Figure 1: SD9251ET Functional Block Diagram.

APPLICATIONS

- Communications
- General-purpose software radios
- I/Q demodulation systems
- Diversity radio systems
- Smart antenna systems
- Multimode digital receivers
- Ultrasound equipment
- Radar/LiDAR applications
- Test and Measurement

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SPECIFICATIONS

DC Specifications

At $T_A = 25^\circ\text{C}$, $V_{AVDD} = 1.8\text{V}$, $V_{DRVDD} = 1.8\text{V}$, $F_{CLK} = 20\text{MHz}$, $A_{IN} = -1\text{dBFS}$, differential AC-coupled external clock source, LVDS mode, unless otherwise noted.

Table 1. DC Specifications.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|-------------------------------------|------|-------|------------|-----------|---------------|
| Resolution | | | 14 | | bits |
| Accuracy | | | | | |
| No Missing Codes | Full | | Guaranteed | | |
| Offset Error | Full | -0.50 | | 0.50 | %FSR |
| Gain Error | Full | -3.50 | | 1.50 | %FSR |
| DNL | Full | | | ± 1.4 | LSB |
| INL | Full | | | ± 2.8 | LSB |
| Matching | | | | | |
| Offset Error | 25°C | -0.70 | | 0.70 | %FSR |
| Gain Error | 25°C | -0.40 | | 0.40 | %FSR |
| Temperature Drift | | | | | |
| Offset Error | Full | | 0.1 | | ppm/°C |
| Gain Error | Full | | 80.0 | | ppm/°C |
| Internal Voltage Reference | | | | | |
| Output Voltage | Full | 0.99 | | 1.05 | V |
| External Voltage Reference | | | | | |
| Range | Full | 0.90 | | 1.07 | V |
| Input Referred Noise | | | | | |
| $V_{REF} = 1.0\text{V}$ | 25°C | | 1.12 | | LSB(rms) |
| Analog Input | | | | | |
| Input Span, $V_{REF} = 1.0\text{V}$ | Full | | 1.8 | | V |
| Input Capacitance | Full | | 6.0 | | pF |
| Input Resistance | Full | | 2.0 | | k Ω |
| Input Common-Mode Voltage | Full | | 0.70 | | V |
| Input Common-Mode Range | Full | 0.65 | | 0.75 | V |
| VCM Voltage | Full | | 0.70 | | V |
| VCM Current Capability | Full | | 100 | | μA |
| Reference Input Resistance | Full | | 50 | | k Ω |
| Power Supply | | | | | |
| V_{AVDD} | Full | 1.7 | 1.8 | 1.9 | V |
| V_{DRVDD} (CMOS) | Full | 1.7 | 1.8 | 3.6 | V |
| V_{DRVDD} (LVDS) | Full | 1.7 | 1.8 | 1.9 | V |
| I_{AVDD} @1.8V | Full | | 153 | 195 | mA |
| I_{DRVDD} @1.8V (CMOS) | Full | | 4 | 5 | mA |
| I_{DRVDD} @1.8V (LVDS) | Full | | 48 | 65 | mA |
| Power Consumption | | | | | |
| Sine Wave Input (CMOS) | Full | | 290 | | mW |
| Sine Wave Input (LVDS) | Full | | 370 | | mW |
| Stand-by ¹ | Full | | 60 | | mW |
| Power Down | Full | | 10.0 | | mW |

¹ Stand-by power is measured with a sinewave input and active clock.

Preliminary

AC Specifications

At $T_A = 25^\circ\text{C}$, $V_{AVDD} = 1.8\text{V}$, $V_{DRVDD} = 1.8\text{V}$, $F_{CLK} = 20\text{MHz}$, $A_{IN} = -1\text{dBFS}$, differential AC-coupled external clock source, High-Performance Calibration Mode enabled, background calibration enabled, LVDS mode, unless otherwise noted.

Table 2. AC Performance Specifications.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|---|--------------------|------|--------|-------|------|
| Signal-to-Noise Ratio (SNR) | | | | | |
| $f_{IN} = 6.55\text{MHz}$ | 25°C | | 73.3 | | dBFS |
| $f_{IN} = 30.2\text{MHz}$ | 25°C | | 73.1 | | dBFS |
| | Full | 71.9 | | | dBFS |
| $f_{IN} = 70.2\text{MHz}$ | 25°C | | 72.7 | | dBFS |
| $f_{IN} = 220\text{MHz}$ | 25°C | | 69.3 | | dBFS |
| Signal-to-Noise and Distortion Ratio (SNDR) | | | | | |
| $f_{IN} = 6.55\text{MHz}$ | 25°C | | 73.3 | | dBFS |
| $f_{IN} = 30.2\text{MHz}$ | 25°C | | 73.0 | | dBFS |
| | Full | 71.8 | | | dBFS |
| $f_{IN} = 70.2\text{MHz}$ | 25°C | | 72.6 | | dBFS |
| $f_{IN} = 220\text{MHz}$ | 25°C | | 69.1 | | dBFS |
| Effective Number of Bits (ENOB) | | | | | |
| $f_{IN} = 6.55\text{MHz}$ | 25°C | | 11.9 | | bits |
| $f_{IN} = 30.2\text{MHz}$ | 25°C | | 11.8 | | bits |
| $f_{IN} = 70.2\text{MHz}$ | 25°C | | 11.8 | | bits |
| $f_{IN} = 220\text{MHz}$ | 25°C | | 11.2 | | bits |
| Worst 2 nd or 3 rd Harmonic Power | | | | | |
| $f_{IN} = 6.55\text{MHz}$ | 25°C | | -91.0 | | dBc |
| $f_{IN} = 30.2\text{MHz}$ | 25°C | | -91.0 | -87.0 | dBc |
| $f_{IN} = 70.2\text{MHz}$ | 25°C | | -91.0 | | dBc |
| $f_{IN} = 220\text{MHz}$ | 25°C | | -87.0 | | dBc |
| Worst Non-Harmonic Power | | | | | |
| $f_{IN} = 6.55\text{MHz}$ | 25°C | | -95.0 | | dBc |
| $f_{IN} = 30.2\text{MHz}$ | 25°C | | -95.0 | | dBc |
| $f_{IN} = 70.2\text{MHz}$ | 25°C | | -95.0 | | dBc |
| $f_{IN} = 220\text{MHz}$ | 25°C | | -82.0 | | dBc |
| Spurious-Free Dynamic Range ¹ (SFDR) | | | | | |
| $f_{IN} = 6.55\text{MHz}$ | 25°C | | 91.0 | | dBc |
| $f_{IN} = 30.2\text{MHz}$ | 25°C | | 91.0 | | dBc |
| | Full | 86.0 | | | dBc |
| $f_{IN} = 70.2\text{MHz}$ | 25°C | | 91.0 | | dBc |
| $f_{IN} = 220\text{MHz}$ | 25°C | | 80.0 | | dBc |
| Two-Tone SFDR | | | | | |
| $f_{IN1} = 29.1\text{MHz}$, $f_{IN2} = 30.6\text{MHz}$ | 25°C | | 90.5 | | dBc |
| Crosstalk ² | 25°C | | -105.0 | | dBc |
| Analog Input Bandwidth | Full | | 650.0 | | MHz |

¹ SNR, SNDR and SFDR exclude the DC and $f_s/2$ bins.

² Crosstalk is measured at 100MHz with -1.0dBFS on one channel and no input on the alternate channel.

Digital Specification

$V_{AVDD} = 1.8V$, $V_{DRVDD} = 1.8V$, $F_{CLK} = 20MHz$, $A_{IN} = -1dBFS$, differential AC-coupled external clock source, DCS disabled, unless otherwise noted.

Table 3. Differential Clock Input.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|----------------------------|------|------------------|-----|----------------|------------|
| Logic Compliance | Full | CMOS/LVDS/LVPECL | | | |
| Internal Common-Mode Bias | Full | | 0.9 | | V |
| Differential Input Voltage | Full | 0.3 | | 1.2 | V_{p-p} |
| Input Voltage Range | Full | $V_{AGND}-0.3$ | | $V_{AVDD}+0.2$ | V |
| Input Common-Mode Range | Full | 0.75 | | 1.05 | V |
| High Level Input Current | Full | -10 | | 10 | μA |
| Low Level Input Current | Full | -10 | | 10 | μA |
| Input Capacitance | Full | | 1.7 | | pF |
| Input Resistance | Full | | 6.0 | | k Ω |

Table 4. SYNC Input.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|--------------------------|------|------------|-----|------------|------------|
| Logic Compliance | Full | CMOS | | | |
| Input Voltage Range | Full | V_{AGND} | | V_{AVDD} | V |
| High Level Input Voltage | Full | 1.22 | | V_{AVDD} | V |
| Low Level Input Voltage | Full | V_{AGND} | | 0.50 | V |
| High Level Input Current | Full | -1 | | 1 | μA |
| Low Level Input Current | Full | -1 | | 1 | μA |
| Input Capacitance | Full | | 1.5 | | pF |
| Input Resistance | Full | | 100 | | k Ω |

Table 5. CSB Input.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|--------------------------|------|------|-----|-----|------------|
| High Level Input Voltage | Full | 1.22 | | | V |
| Low Level Input Voltage | Full | | | 0.6 | V |
| High Level Input Current | Full | -1 | | 1 | μA |
| Low Level Input Current | Full | -1 | | 1 | μA |
| Input Capacitance | Full | | 1.5 | | pF |
| Input Resistance | Full | | 100 | | k Ω |

Table 6. SCLK/DFS Input.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|--------------------------|------|------|-----|-----|------------|
| High Level Input Voltage | Full | 1.22 | | | V |
| Low Level Input Voltage | Full | | | 0.6 | V |
| High Level Input Current | Full | -1 | | 1 | μA |
| Low Level Input Current | Full | -1 | | 1 | μA |
| Input Capacitance | Full | | 1.5 | | pF |
| Input Resistance | Full | | 100 | | k Ω |

Table 7. SDIO/DCS Input.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|--------------------------|------|------|-----|-----|------------|
| High Level Input Voltage | Full | 1.22 | | | V |
| Low Level Input Voltage | Full | | | 0.6 | V |
| High Level Input Current | Full | -1 | | 1 | μ A |
| Low Level Input Current | Full | -1 | | 1 | μ A |
| Input Capacitance | Full | | 1.5 | | pF |
| Input Resistance | Full | | 100 | | k Ω |

Table 8. OEB Input.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|--------------------------|------|------|-----|-----|------------|
| High Level Input Voltage | Full | 1.22 | | | V |
| Low Level Input Voltage | Full | | | 0.6 | V |
| High Level Input Current | Full | -1 | | 1 | μ A |
| Low Level Input Current | Full | -1 | | 1 | μ A |
| Input Capacitance | Full | | 1.5 | | pF |
| Input Resistance | Full | | 100 | | k Ω |

Table 9. PDWN Input.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|--------------------------|------|------|-----|-----|------------|
| High Level Input Voltage | Full | 1.22 | | | V |
| Low Level Input Voltage | Full | | | 0.6 | V |
| Pull-down Current @1.8V | Full | | | 90 | μ A |
| Input Capacitance | Full | | 1.5 | | pF |
| Input Resistance | Full | | 28 | | k Ω |

Table 10. CMOS Outputs (DATA and OR).

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|---------------------------------------|------|------|-----|------|------|
| DRVDD = 3.3V | | | | | |
| High Level Output Voltage @50 μ A | Full | 3.20 | | | V |
| High Level Output Voltage @0.5mA | Full | 3.10 | | | V |
| Low Level Output Voltage @50 μ A | Full | | | 0.05 | V |
| Low Level Output Voltage @1.6mA | Full | | | 0.10 | V |
| DRVDD = 1.8V | | | | | |
| High Level Output Voltage @50 μ A | Full | 1.77 | | | V |
| High Level Output Voltage @0.5mA | Full | 1.75 | | | V |
| Low Level Output Voltage @50 μ A | Full | | | 0.05 | V |
| Low Level Output Voltage @1.6mA | Full | | | 0.10 | V |

Table 11. LVDS Outputs (DATA and OR).

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|---|------|------|------|------|------|
| Differential Output Voltage (V_{OD}), ANSI Mode | Full | 250 | 300 | 450 | mV |
| Output Offset Voltage (V_{OS}), ANSI Mode | Full | 1.10 | 1.13 | 1.30 | V |
| Differential Output Voltage (V_{OD}), Reduced Swing | Full | 150 | 220 | 285 | mV |
| Output Offset Voltage (V_{OS}), Reduced Swing | Full | 1.10 | 1.22 | 1.30 | V |

Switching Specifications

$V_{AVDD} = 1.8V$, $V_{DRVDD} = 1.8V$, $F_{CLK} = 20MHz$, $A_{IN} = -1dBFS$, differential AC-coupled sine wave external clock source, DCS enabled, unless otherwise noted.

Table 12. Clock Input Timing.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|---|------|------|-------|------|------|
| Input Clock Rate | Full | | | 160 | MHz |
| Conversion Rate (after clock divider) | Full | 3.0 | | 20.0 | MHz |
| <i>CLK Pulse Width High (t_{CH})</i> | | | | | |
| Divide-by-1 Mode, DCS Enabled | Full | 1.5 | | | ns |
| Divide-by-1 Mode, DCS Disabled | Full | 22.0 | 25.0 | 28.0 | ns |
| Divide-by-2 Mode Through Divide-by-8 Mode | Full | 1.5 | | | ns |
| Aperture Delay (t_A) | Full | | 0.5 | | ns |
| Aperture Uncertainty (Jitter, t_J) | Full | | 140.0 | | fs |

Table 13. SYNC Timing Requirements.

| PARAMETER | MIN | TYP | MAX | UNIT |
|------------------------------|-----|------|-----|------|
| Set-Up Time ($t_{S,SYNC}$) | | 0.35 | | ns |
| Hold Time ($t_{H,SYNC}$) | | 0.35 | | ns |

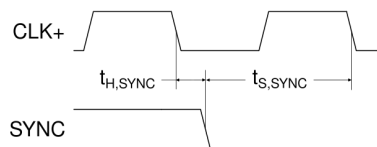


Figure 2: SYNC Input Timing.

Table 14. Data Output.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|---|------|------|---------|-----|---------|
| <i>CMOS Mode</i> | | | | | |
| Data Propagation Delay (t_{PD}) | Full | | 6.0 | | ns |
| DCO Propagation Delay (t_{DCO}) | Full | | 7.0 | | ns |
| DCO to Data Skew (t_{SKEW}) | Full | 0.3 | 1.2 | 2.2 | ns |
| Pipeline Delay (Latency, L) | Full | | 35.0 | | Cycles |
| <i>LVDS Mode</i> | | | | | |
| Data Propagation Delay (t_{PD}) | Full | | 8.0 | | ns |
| DCO Propagation Delay (t_{DCO}) | Full | | 7.7 | | ns |
| DCO to Data Skew (t_{SKEW}) | Full | -0.5 | 0.1 | 0.7 | ns |
| Pipeline Delay (Latency, L) Channel A/Channel B | Full | | 32/32.5 | | Cycles |
| Wake-Up Time (from sleep) | Full | | 5.0 | | μs |
| Wake-Up Time (from power down) | Full | | 600.0 | | μs |
| Out-of-Range Recovery Time | Full | | 3 | | Cycles |

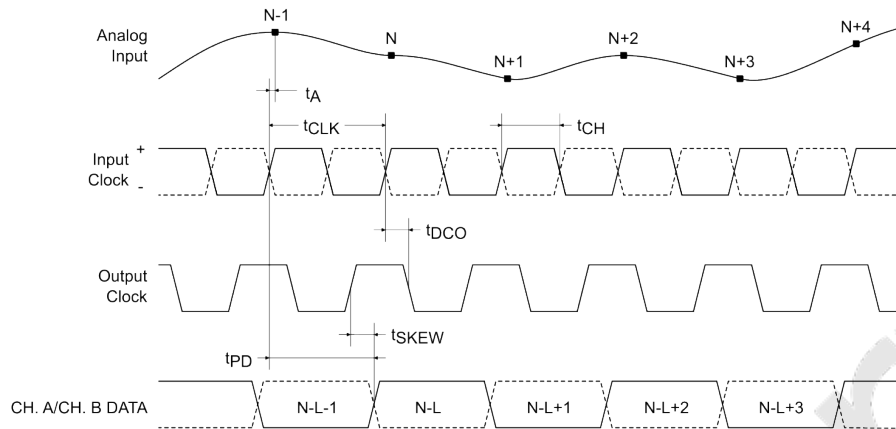


Figure 3: Parallel CMOS Output Mode Timing.

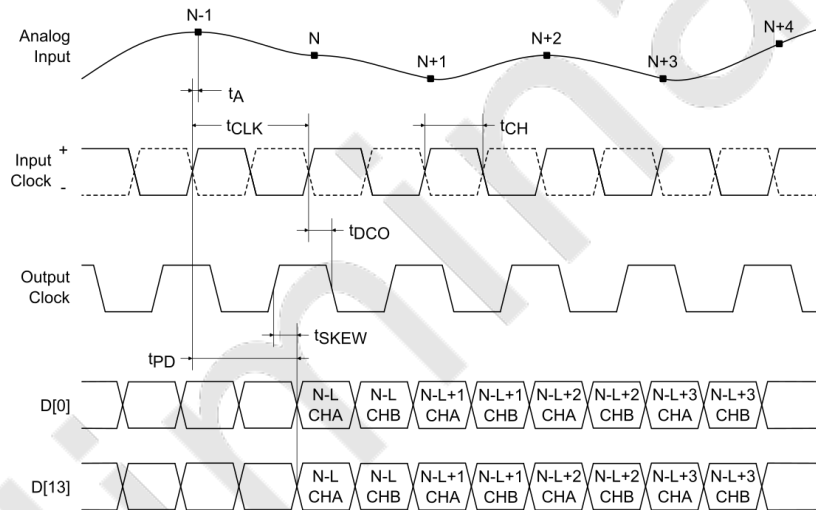


Figure 4: Parallel LVDS Output Mode Timing.

Output Modes

The SD9251ET supports both CMOS and LVDS interfaces. Two LVDS samples are sent out every clock cycle using both the rising and the falling edge of the output clock. In interleaved parallel mode, the two ADCs share the full set of output pins. The first half-cycle contains ADC A data and the second ADC B data. In multiplexed mode, each ADC has its dedicated set of output pins and the data is sent out even numbered bits on the first half-cycle and the odd bits on the second. Register `0x465`, bits [2:0], control the interleaving/multiplexing (see register description for details). The ADC B overrange bit is not available in channel multiplexed mode, for the LVDS interface.

Output Timing Control

Data delay control, bits [8:5], in register `0x473`, can be used to move the CMOS data relative to output clock. Bit [9] inverts the internal clock sending the data out. Bits [13:10], in register `0x473`, control the output clock delay relative to output data, while bit [14] inverts the clock. The delay step size is about 250ps.

Data delay control is not available in interleaved or multiplexed output mode.

Driving long traces or large load capacitance with CMOS output produces voltage ripple in the digital IO supply and ground,

which may couple on chip to the sensitive analog circuits in the ADC and degrade the performance. This effect can be reduced by using an external buffer IC. The use of LVDS output interface largely eliminates issues with IO supply noise.

CMOS→LVDS Conversion

The output interface can be converted to LVDS using the register writes in Table 15, where each IO pad is programmed to a LVDS driver.

Table 15. Output Mode Conversion (CMOS→LVDS).

| Register | Value | Register | Value | Register | Value | Register | Value |
|----------|--------|----------|-------|--------------|--------|--------------|-------|
| 0x401 | 0xc3 | 0x403 | 0xe1 | 0x405 | 0xe1 | 0x407 | 0xe1 |
| 0x409 | 0xe1 | 0x40b | 0xe1 | 0x40d | 0xcac1 | 0x40f | 0xe1 |
| 0x411 | 0xcac1 | 0x413 | 0xe1 | 0x415 | 0xcec1 | 0x417 | 0xe1 |
| 0x419 | 0xcac1 | 0x41b | 0xe1 | 0x41d | 0xcec1 | 0x41f | 0xe1 |
| 0x421 | 0xcec1 | 0x423 | 0xe1 | 0x425 | 0xcac1 | 0x427 | 0xe1 |
| 0x429 | 0xc6c1 | 0x42b | 0xe1 | 0x42d | 0xcec1 | 0x42f | 0xe1 |
| 0x431 | 0xc6c1 | 0x433 | 0xe1 | 0x435 | 0xd2c1 | 0x437 | 0xe1 |
| 0x439 | 0xcac1 | 0x43b | 0xe1 | 0x43d | 0xd2c1 | 0x43f | 0xe1 |
| 0x441 | 0xcac1 | 0x443 | 0xe1 | 0x445 | 0xcac1 | 0x447 | 0xe1 |
| 0x449 | 0xcec1 | 0x44b | 0xe1 | 0x44d | 0xc3 | 0x44f | 0xc3 |
| 0x451 | 0xc3 | 0x453 | 0xc3 | 0x466 bit[0] | 0x1 | 0x466 bit[2] | 0x0 |

ABSOLUTE MAXIMUM RATINGS

Table 16. Absolute Maximum Ratings ($T_A = 25^\circ\text{C}$, unless otherwise specified).

| Parameter | Symbol | Conditions | Min | Max | Units |
|---|-------------|------------------|------|-----|-------|
| AVDD | V_{AVDD} | Relative to AGND | -0.3 | 2.0 | V |
| DRVDD | V_{DRVDD} | Relative to AGND | -0.3 | 3.8 | V |
| VINAP/VINBP, VINAM/VINBM | | Relative to AGND | -0.3 | 2.0 | V |
| CLK+, CLK- | | Relative to AGND | -0.3 | 2.0 | V |
| SYNC | | Relative to AGND | -0.3 | 2.0 | V |
| RBIAS | | Relative to AGND | -0.3 | 2.0 | V |
| SENSE | | Relative to AGND | -0.3 | 2.0 | V |
| VCM | | Relative to AGND | -0.3 | 2.0 | V |
| VREF | | Relative to AGND | -0.3 | 2.0 | V |
| CSB | | Relative to AGND | -0.3 | 3.8 | V |
| SCLK/DFS | | Relative to AGND | -0.3 | 3.8 | V |
| SDIO/DCS | | Relative to AGND | -0.3 | 3.8 | V |
| OEB | | Relative to AGND | -0.3 | 3.8 | V |
| PDWN | | Relative to AGND | -0.3 | 3.8 | V |
| DA0, ..., DA13 DB0, ..., DB13 | | Relative to AGND | -0.3 | 3.8 | V |
| DCOA, DCOB | | Relative to AGND | -0.3 | 3.8 | V |
| Operating Temperature Range (Ambient) | | | -55 | 125 | °C |
| Maximum Junction Temperature Under Bias | | | | 125 | |
| Storage Temperature Range (Ambient) | | | -65 | 150 | |

Notes:

- Stresses beyond those listed under Table 16 may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- The device passed product qualification in accordance with JESD47. Specifically, High-Temperature Operating Life (HTOL), qualification in accordance with JESD22-A108 testing was performed at a junction temperature of $T_j = 125^\circ\text{C}$ for 1000 hours across three independent production lots, with sample size of 77 units per lot (231 units total). No failures were observed during full qualification, demonstrating compliance with industry reliability requirements.

ESD CAUTION.



Electrostatic Discharge Sensitive Device.

Proper ESD precautions should be observed to prevent performance degradation or loss of functionality.

PACKAGE

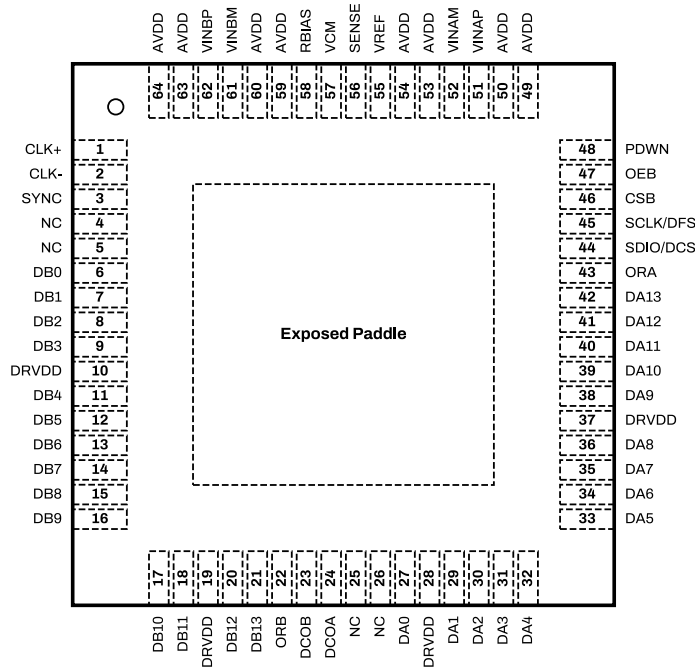


Figure 5: SD9251ET Package Top View for Parallel CMOS Configuration.

1. The exposed thermal pad on the bottom of the package provides the analog ground for the part and must be connected for proper operation.

Table 17. Pin Descriptions for Parallel CMOS Configuration.

| Number | Name | Type | Comment |
|----------------|-------|--------|-------------------------------------|
| 0 | AGND | Ground | Exposed Paddle, Analog Ground. |
| 1 | CLK+ | Input | ADC Clock Input (Plus). |
| 2 | CLK- | Input | ADC Clock Input (Minus). |
| 3 | SYNC | Input | Digital Synchronization Pin. |
| 4, 5, 25, 26 | NC | | Do not connect. |
| 6 | DB0 | Output | Channel B CMOS Output Data 0 (LSB). |
| 7 | DB1 | Output | Channel B CMOS Output Data 1. |
| 8 | DB2 | Output | Channel B CMOS Output Data 2. |
| 9 | DB3 | Output | Channel B CMOS Output Data 3. |
| 10, 19, 28, 37 | DRVDD | Power | Digital I/O Supply. |
| 11 | DB4 | Output | Channel B CMOS Output Data 4. |
| 12 | DB5 | Output | Channel B CMOS Output Data 5. |
| 13 | DB6 | Output | Channel B CMOS Output Data 6. |
| 14 | DB7 | Output | Channel B CMOS Output Data 7. |
| 15 | DB8 | Output | Channel B CMOS Output Data 8. |
| 16 | DB9 | Output | Channel B CMOS Output Data 9. |
| 17 | DB10 | Output | Channel B CMOS Output Data 10. |

| Number | Name | Type | Comment |
|--------------------------------------|----------|--------|--|
| 18 | DB11 | Output | Channel B CMOS Output Data 11. |
| 20 | DB12 | Output | Channel B CMOS Output Data 12. |
| 21 | DB13 | Output | Channel B CMOS Output Data 13. |
| 22 | ORB | Output | Channel B Overrange Output. |
| 23 | DCOB | Output | Channel B Data Clock Output. |
| 24 | DCOA | Output | Channel A Data Clock Output. |
| 27 | DA0 | Output | Channel A CMOS Output Data 0 (LSB). |
| 29 | DA1 | Output | Channel A CMOS Output Data 1. |
| 30 | DA2 | Output | Channel A CMOS Output Data 2. |
| 31 | DA3 | Output | Channel A CMOS Output Data 3. |
| 32 | DA4 | Output | Channel A CMOS Output Data 4. |
| 33 | DA5 | Output | Channel A CMOS Output Data 5. |
| 34 | DA6 | Output | Channel A CMOS Output Data 6. |
| 35 | DA7 | Output | Channel A CMOS Output Data 7. |
| 36 | DA8 | Output | Channel A CMOS Output Data 8. |
| 38 | DA9 | Output | Channel A CMOS Output Data 9. |
| 39 | DA10 | Output | Channel A CMOS Output Data 10. |
| 40 | DA11 | Output | Channel A CMOS Output Data 11. |
| 41 | DA12 | Output | Channel A CMOS Output Data 12. |
| 42 | DA13 | Output | Channel A CMOS Output Data 13. |
| 43 | ORA | Output | Channel A Overrange Output. |
| 44 | SDIO/DCS | InOut | SPI Serial Data I/O/Duty Cycle Stabilizer Pin in External Pin Mode. |
| 45 | SCLK/DFS | Input | SPI Serial Clock/Data Format Select Pin in External Pin Mode. |
| 46 | CSB | Input | SPI Chip Select (Active Low). |
| 47 | OEB | Input | Output Enable Input (Active low). |
| 48 | PDWN | Input | Power-Down Input (Active High). The operation of this pin depends on the SPI mode and can be configured as power-down or stand-by. |
| 49, 50, 53, 54, 59, 60, 63, 64 | AVDD | Power | Analog Power Supply (1.8 V Nominal). |
| 51 | VINAP | Input | Differential Analog Input Pin (Plus) for Channel A. |
| 52 | VINAM | Input | Differential Analog Input Pin (Minus) for Channel A. |
| 55 | VREF | InOut | Voltage Reference Input/Output. |
| 56 | SENSE | Input | Reference Programming Pin. |
| 57 | VCM | Output | This pin outputs the common-mode voltage that can be used externally to bias the analog input pins. |
| 58 | RBIAS | InOut | External Reference Bias Resistor. Connect to 30 kΩ (1% tolerance) resistor to ground. |
| 61 | VINBM | Input | Differential Analog Input Pin (Minus) for Channel B. |
| 62 | VINBP | Input | Differential Analog Input Pin (Plus) for Channel B. |

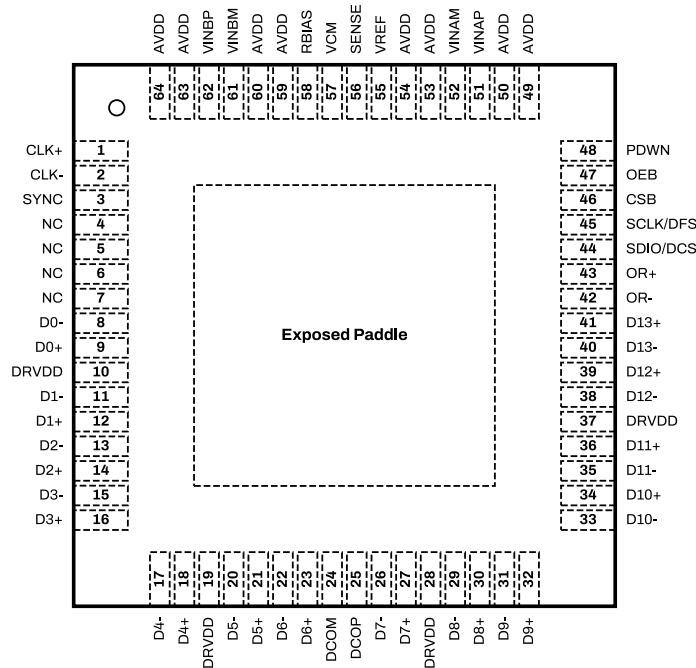


Figure 6: SD9251ET Package Top View for Parallel LVDS Configuration.

1. The exposed thermal pad on the bottom of the package provides the analog ground for the part and must be connected for proper operation.

Table 18. Pin Descriptions for Parallel LVDS Configuration.

| Number | Name | Type | Comment |
|----------------|-------|--------|---|
| 0 | AGND | Ground | Exposed Paddle, Analog Ground. |
| 1 | CLK+ | Input | ADC Clock Input (Plus). |
| 2 | CLK- | Input | ADC Clock Input (Minus). |
| 3 | SYNC | Input | Digital Synchronization Pin. |
| 4, 5, 6, 7 | NC | | Do not connect. |
| 8 | D0- | Output | Channel A/Channel B LVDS Output Data 0 (Minus). |
| 9 | D0+ | Output | Channel A/Channel B LVDS Output Data 0 (Plus). |
| 10, 19, 28, 37 | DRVDD | Power | Digital I/O Supply. |
| 11 | D1- | Output | Channel A/Channel B LVDS Output Data 1 (Minus). |
| 12 | D1+ | Output | Channel A/Channel B LVDS Output Data 1 (Plus). |
| 13 | D2- | Output | Channel A/Channel B LVDS Output Data 2 (Minus). |
| 14 | D2+ | Output | Channel A/Channel B LVDS Output Data 2 (Plus). |
| 15 | D3- | Output | Channel A/Channel B LVDS Output Data 3 (Minus). |
| 16 | D3+ | Output | Channel A/Channel B LVDS Output Data 3 (Plus). |
| 17 | D4- | Output | Channel A/Channel B LVDS Output Data 4 (Minus). |
| 18 | D4+ | Output | Channel A/Channel B LVDS Output Data 4 (Plus). |
| 20 | D5- | Output | Channel A/Channel B LVDS Output Data 5 (Minus). |
| 21 | D5+ | Output | Channel A/Channel B LVDS Output Data 5 (Plus). |
| 22 | D6- | Output | Channel A/Channel B LVDS Output Data 6 (Minus). |

| Number | Name | Type | Comment |
|--------------------------------------|----------|--------|--|
| 23 | D6+ | Output | Channel A/Channel B LVDS Output Data 6 (Plus). |
| 24 | DCOM | Output | LVDS Clock Output (Minus). |
| 25 | DCOP | Output | LVDS Clock Output (Plus). |
| 26 | D7- | Output | Channel A/Channel B LVDS Output Data 7 (Minus). |
| 27 | D7+ | Output | Channel A/Channel B LVDS Output Data 7 (Plus). |
| 29 | D8- | Output | Channel A/Channel B LVDS Output Data 8 (Minus). |
| 30 | D8+ | Output | Channel A/Channel B LVDS Output Data 8 (Plus). |
| 31 | D9- | Output | Channel A/Channel B LVDS Output Data 9 (Minus). |
| 32 | D9+ | Output | Channel A/Channel B LVDS Output Data 9 (Plus). |
| 33 | D10- | Output | Channel A/Channel B LVDS Output Data 10 (Minus). |
| 34 | D10+ | Output | Channel A/Channel B LVDS Output Data 10 (Plus). |
| 35 | D11- | Output | Channel A/Channel B LVDS Output Data 11 (Minus). |
| 36 | D11+ | Output | Channel A/Channel B LVDS Output Data 11 (Plus). |
| 38 | D12- | Output | Channel A/Channel B LVDS Output Data 12 (Minus). |
| 39 | D12+ | Output | Channel A/Channel B LVDS Output Data 12 (Plus). |
| 40 | D13- | Output | Channel A/Channel B LVDS Output Data 13 (Minus). |
| 41 | D13+ | Output | Channel A/Channel B LVDS Output Data 13 (Plus). |
| 42 | OR- | Output | Channel A/Channel B LVDS Overage (Minus). |
| 43 | OR+ | Output | Channel A/Channel B LVDS Overage (Plus). |
| 44 | SDIO/DCS | InOut | SPI Serial Data I/O/Duty Cycle Stabilizer Pin in External Pin Mode. |
| 45 | SCLK/DFS | Input | SPI Serial Clock/Data Format Select Pin in External Pin Mode. |
| 46 | CSB | Input | SPI Chip Select (Active Low). |
| 47 | OEB | Input | Output Enable Input (Active low). |
| 48 | PDWN | Input | Power-Down Input (Active High). The operation of this pin depends on the SPI mode and can be configured as power-down or stand-by. |
| 49, 50, 53, 54, 59, 60, 63, 64 | AVDD | Power | Analog Power Supply (1.8 V Nominal). |
| 51 | VINAP | Input | Differential Analog Input Pin (Plus) for Channel A. |
| 52 | VINAM | Input | Differential Analog Input Pin (Minus) for Channel A. |
| 55 | VREF | InOut | Voltage Reference Input/Output. |
| 56 | SENSE | Input | Reference Programming Pin. |
| 57 | VCM | Output | This pin outputs the common-mode voltage that can be used externally to bias the analog input pins. |
| 58 | RBIAS | InOut | External Reference Bias Resistor. Connect to 30 kΩ (1% tolerance) resistor to ground. |
| 61 | VINBM | Input | Differential Analog Input Pin (Minus) for Channel B. |
| 62 | VINBP | Input | Differential Analog Input Pin (Plus) for Channel B. |

TYPICAL PERFORMANCE CHARACTERISTICS

At $T_A = 25^\circ\text{C}$, $V_{AVDD} = 1.8\text{V}$, $V_{DRVDD} = 1.8\text{V}$, $F_{CLK} = 20\text{MHz}$, $A_{IN} = -1\text{dBFS}$, differential AC-coupled clock source, High-Performance Calibration Mode enabled, background calibration enabled, LVDS mode, unless otherwise noted.

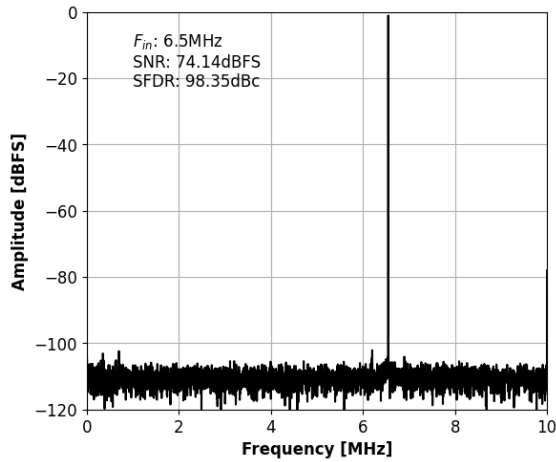


Figure 7: Single-Tone FFT with $f_{IN}=6.55\text{MHz}$.

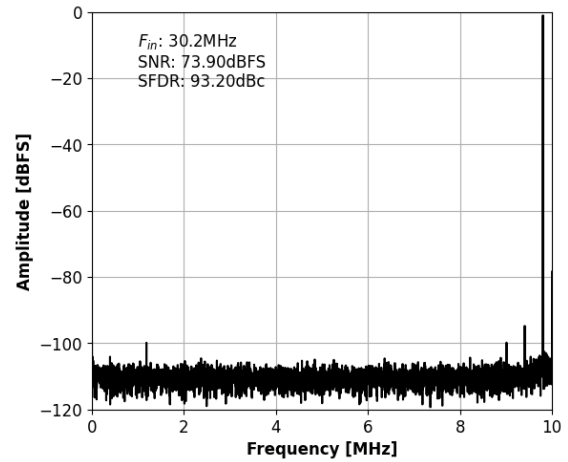


Figure 8: Single-Tone FFT with $f_{IN}=30.2\text{MHz}$.

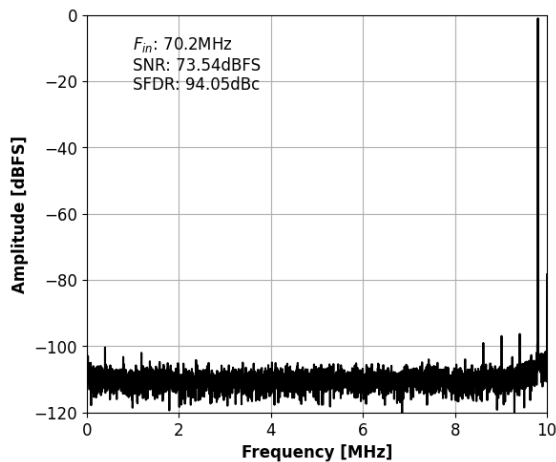


Figure 9: Single-Tone FFT with $f_{IN}=70.2\text{MHz}$.

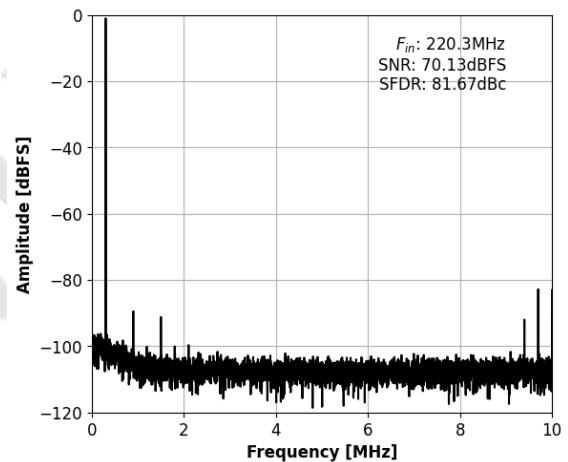


Figure 10: Single-Tone FFT with $f_{IN}=220\text{MHz}$.

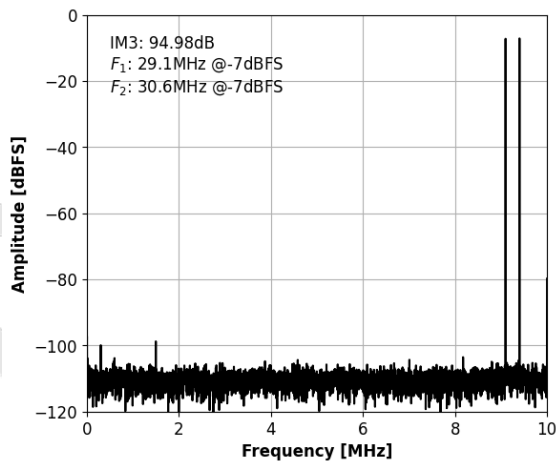


Figure 11: Two-Tone FFT with $f_{IN1}=29.1\text{MHz}$, $f_{IN2}=30.6\text{MHz}$.

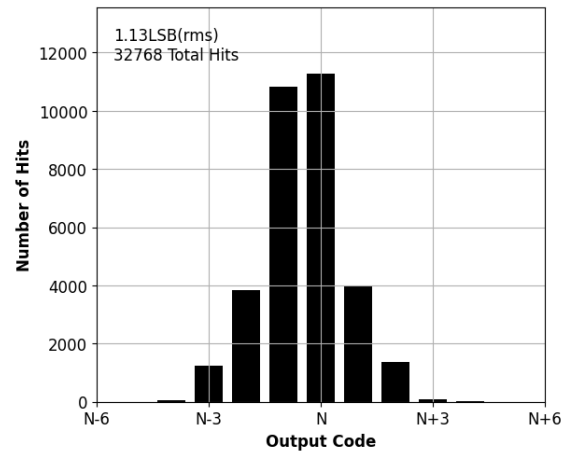


Figure 12: Grounded Input Histogram.

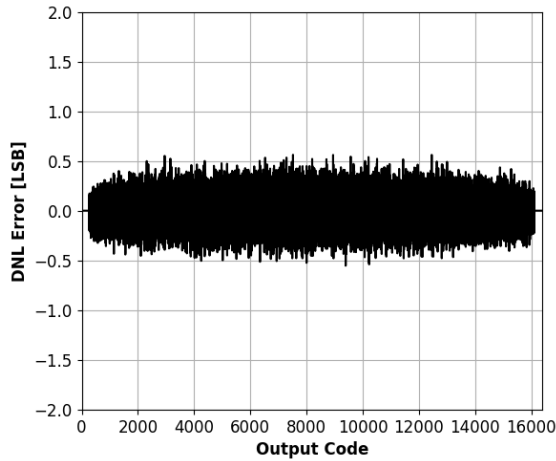


Figure 13: DNL Error with $f_{IN}=6.55\text{MHz}$.

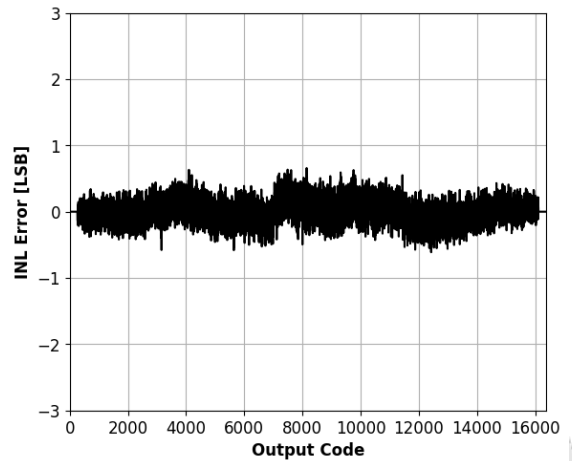


Figure 14: INL Error with $f_{IN}=6.55\text{MHz}$.

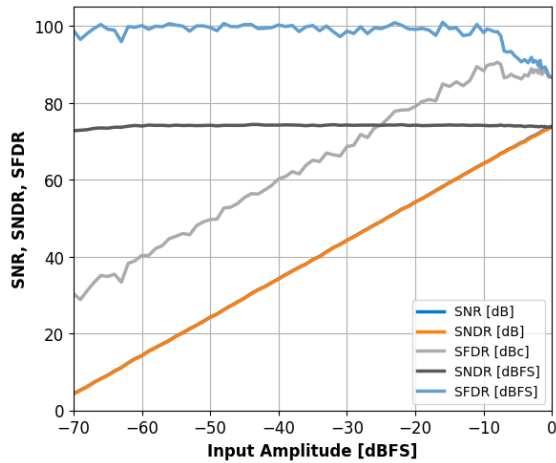


Figure 15: Single-Tone SNR, SNDR and SFDR vs. Input Amplitude with $f_{IN}=30.25\text{MHz}$.

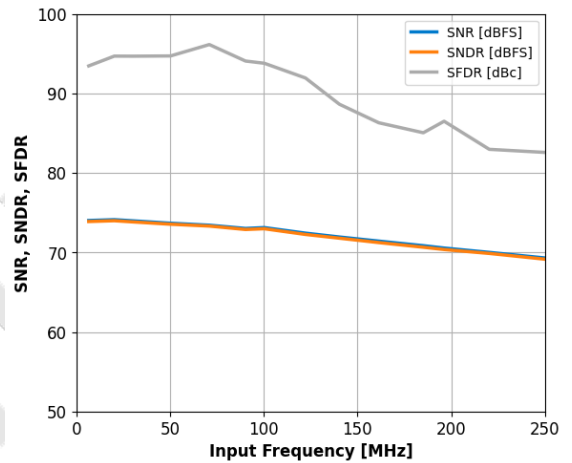


Figure 16: Single-Tone SNR, SNDR and SFDR vs. Input Frequency with $f_S=20\text{MHz}$.

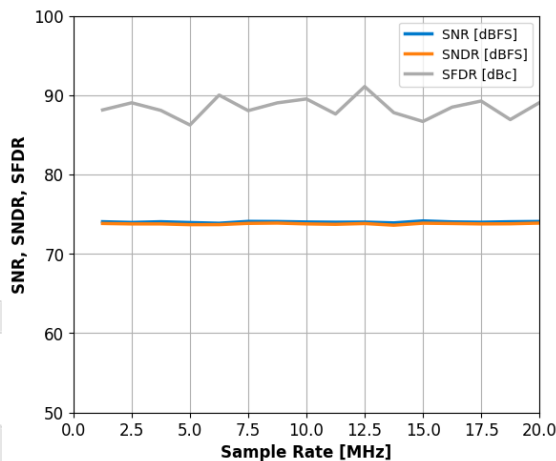


Figure 17: Single-Tone SNR, SNDR and SFDR vs. Sample Rate with $f_{IN}=30.25\text{MHz}$.

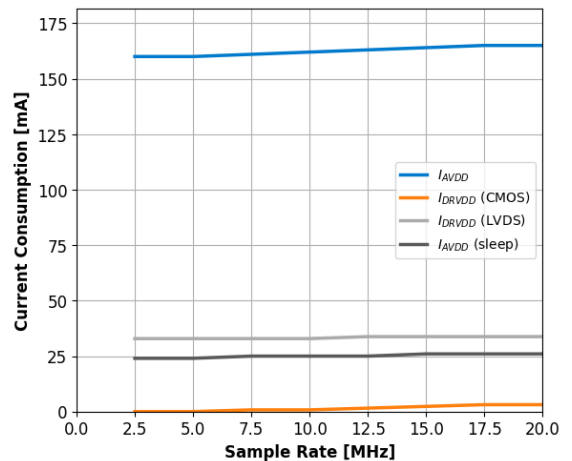


Figure 18: Current vs. Sample Rate.

EQUIVALENT CIRCUITS

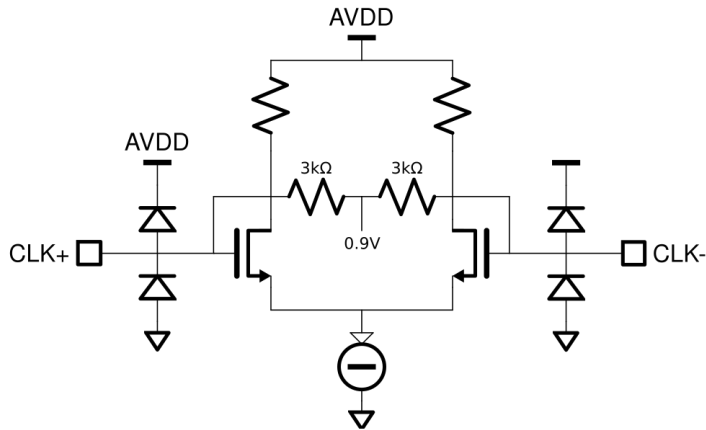


Figure 19: Equivalent Clock Input Circuit.

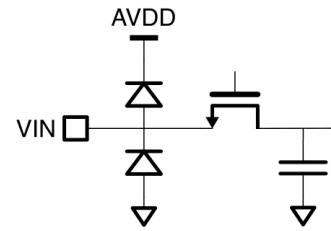


Figure 20: Equivalent Analog Input Circuit.

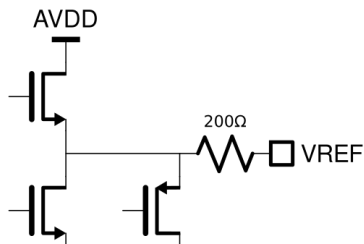


Figure 21: Equivalent VREF Circuit.

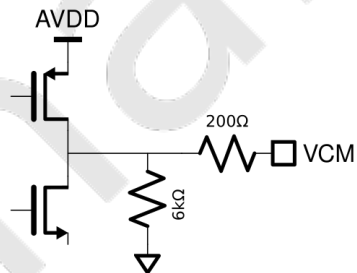


Figure 22: Equivalent VCM Circuit.

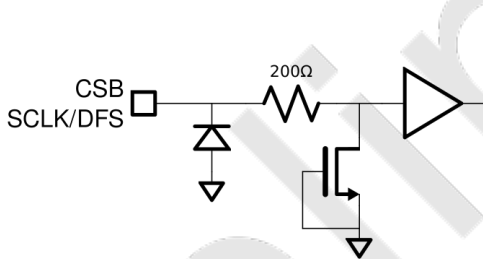


Figure 23: Equivalent CSB or SCLK/DFS Input Circuit.

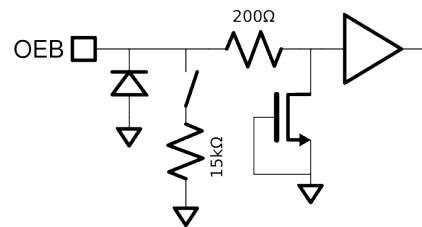


Figure 24: Equivalent OEB Input Circuit.

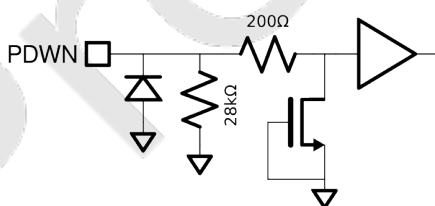


Figure 25: Equivalent PDWN Input Circuit.

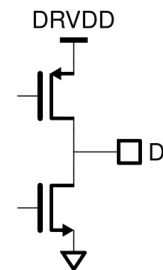


Figure 26: Equivalent Digital Output Circuit.

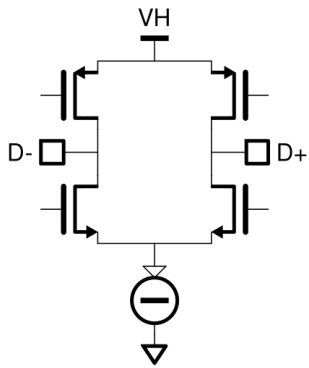


Figure 27: Equivalent LVDS output Circuit.

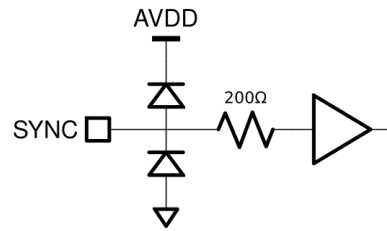


Figure 28: Equivalent SYNC Input Circuit.

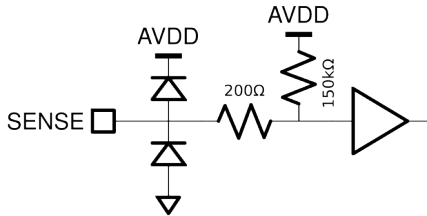


Figure 29: Equivalent SENSE Input Circuit.

THEORY OF OPERATION

ADC Architecture

The ADC uses a pipelined architecture and innovative patented switched-capacitor circuits. Its fully differential design provides exceptional immunity to power supply noise and minimizes reference voltage self-modulation. A built-in Sample-and-Hold (S/H) function is integrated into the input stage of the pipeline structure.

Analog Input

The input stage of the ADC behaves as a switched-capacitor network, presenting itself to the driving circuit as a combination of a switch and a sampling capacitor. The capacitor is reset prior to each conversion cycle, effectively eliminating non-linear memory effects commonly observed in some pipelined ADC architectures. The ADC does not include an internal common-mode bias therefore, the driving source must provide an appropriate common-mode voltage.

Differential Clock Input

The SD9251ET features a differential clock receiver with an integrated common-mode bias. For proper operation, the clock inputs should be AC-coupled using 10nF capacitors.

Differential Clock Configuration. For optimal jitter performance, a differential clock source is recommended. The differential clock signals to CLK+ and CLK- should be connected through a 10nF AC-coupling capacitors.

Single-Ended Clock Configuration. If a single-ended clock source is used, the signal source should be AC-coupled to the CLK+ pin. In this configuration, a 10nF capacitor should be connected between the CLK- pin and analog ground to maintain proper biasing.

Clock Jitter Considerations. Clock jitter has a significant impact on the ADC's signal-to-noise ratio (SNR). The sensitivity to jitter increases with input signal frequency. For best performance, a low-noise differential clock with fast edge transitions should be used.

Note: The part can enter in manufacturing test mode if both differential clock inputs are held low for more than 1ms. This behavior can be prevented by writing 1 to register *0x4cf*, bit[15].

Clock Divider

The ADC includes a programmable clock divider that allows the input clock to be divided by integer values from 2 to 8. The divider is configured by setting register *0x463*, bits [7:5], to the desired division value. A value of 0 (default) bypasses the divider entirely.

By default, the divider starts asynchronously. If the application requires synchronization across multiple ADC devices, the SYNC pin provides means for aligning clock dividers to guarantee sampling on the same clock edge. If clock divider is bypassed, this feature is not needed.

Synchronization is enabled by setting register *0x463*, bit [10], to 1. When the bit is 0, SYNC pin is ignored. SYNC is a level sensitive, active high, reset pin that is captured on the falling edge of the input clock. As long as SYNC is high, the divider stays in reset. It starts dividing on the first falling clock edge after SYNC goes low.

Make sure that the falling edge of SYNC meets the specified setup and hold times relative to the input clock, as shown in Table 13. Pay attention to the length matching of the clock and SYNC routing to the multiple ADC chips. For test and debugging purposes, the level of received and captured SYNC signal can be read from register *0x4ff*, bit [10].

Clock Duty-Cycle Requirements. The ADC utilizes both the rising and falling edges of the input clock (or the divided clock, if the divider is enabled) for internal sampling operations. To achieve optimal performance, especially at the maximum sampling rate, the clock duty cycle should be as close to 50% as possible.

When the divider is enabled with an even divisor, a 50% duty cycle is guaranteed by design. If the application uses a clock with a non-ideal duty cycle, a Duty Cycle Stabilizer (DCS) can be enabled to improve performance.

ADC Self-Calibration

The ADC includes an automatic calibration mechanism that is executed at power-up to ensure optimal performance. It calibrates out capacitor mismatch and the effects of operational amplifier finite gain and bandwidth. For best results, calibration should be performed at the actual sampling rate used during operation. To support this, the device continuously monitors the sampling clock frequency and automatically re-triggers calibration if a significant change is detected. This feature can be disabled by setting register *0x4c9*, bit[0], to 1.

Manual calibration can also be initiated by toggling both *0xdc1*, bit[4] and *0xcc1*, bit[4] from 0 to 1. The calibration process is implemented using a state-machine architecture, ensuring a deterministic and predictable calibration time. By default the calibration takes 46 million ADC sampling clock cycles. Calibration completion status can be read from *0xdef*, bit[0], for the first ADC and *0xcef*, bit[0], for the second ADC after the status readback is enabled by writing *0x1c* to both *0xdeb* and *0xceb*. Bit value 1 indicates that calibration is complete.

In addition, the ADC supports a Background Calibration (BGC) mode, which is disabled by default. When enabled, parameters for compensating changes in operational amplifier gain and bandwidth are continuously updated. BGC is beneficial in environments with large temperature variations near the hot end of the specified operating temperature range. For its operation, BGC uses a dither signal which is injected into the ADC input signal path. This dither consumes approximately 0.8dB of the ADC's input range, resulting in earlier clipping compared to when BGC is disabled. When BGC is enabled calibration completion status bit remains 0.

To enable BGC:

- Write *0b01* to register *0xde1*, bits [15:14]
- Write *0b01* to register *0xce1*, bits [15:14]
- Write *0x0d80* to register *0xdcf*
- Write *0x0d80* to register *0xccf*
- Write *0b0* to register *0xde3*, bit [3]
- Write *0b0* to register *0xce3*, bit [3]

Calibration parameters can be altered to optimize ADC performance and the duration of the calibration according to Table 19. High Performance settings improve the low frequency SFDR compared to the default settings while the High Speed Settings minimize the calibration time at the cost of small SFDR and SNDR degradation. If the parameters are altered, the calibration has to be reinitiated as described earlier.

Table 19. Calibration Settings.

| Register Address | Default Value | High Performance Value | High Speed Value |
|-------------------------|---------------|------------------------|------------------|
| <i>0xccd</i> | <i>0x1483</i> | <i>0x3483</i> | <i>0x348c</i> |
| <i>0xcd5</i> | <i>0x1483</i> | <i>0x3483</i> | <i>0x348c</i> |
| <i>0xcd</i> | <i>0x16c3</i> | <i>0x36c3</i> | <i>0x36cc</i> |
| <i>0xce1</i> | <i>0xbbe8</i> | <i>0xbb80</i> | <i>0xbb20</i> |
| <i>0xcd</i> | <i>0x1483</i> | <i>0x3483</i> | <i>0x348c</i> |
| <i>0xdd5</i> | <i>0x1483</i> | <i>0x3483</i> | <i>0x348c</i> |
| <i>0xdd</i> | <i>0x16c3</i> | <i>0x36c3</i> | <i>0x36cc</i> |
| <i>0xde1</i> | <i>0xbbe8</i> | <i>0xbb80</i> | <i>0xbb20</i> |
| Duration (clock cycles) | 46M | 25M | 6.3M |

Stand-by and Power-Down Modes

The SD9251ET supports two power-saving modes, power down and stand-by, that can be used when the ADCs are not actively sampling. In both modes, the SPI interface (if enabled) remains operational.

Power-Down Mode. This mode disables most of the internal circuitry, resulting in the lowest residual supply current. It is ideal for applications requiring minimal power consumption during idle periods. Power-down mode can be enabled via:

- The PDWN pin when operating in the external pin mode, or
- Setting register *0x457*, bit[7], to 1.

Stand-by Mode. Stand-by mode offers a faster wake-up time compared to power-down mode, at the cost of slightly higher residual current. It is suitable for applications that require rapid recovery from idle states. To enable stand-by mode, set register *0x457*, bits [3] and [8], to 1.

Note: It is recommended to disable the ADC auto-calibration when using stand-by mode to avoid unintended calibration cycles during transitions.

Commonly Used Functions

The SD9251ET offers several functions available via dual function pin controls (external pin mode vs. SPI mode). The SD9251ET detects the SPI mode during the first SPI transaction after power-up. If the user does not want to program the device via the SPI interface, the dual function is available.

Duty-Cycle Stabilizer. The Duty-Cycle Stabilizer (DCS) retimes the falling edge of the clock thus providing an internal clock signal with a 50% duty cycle. The DCS is useful in systems where the input clock has an uneven duty cycle. It can be enabled in the following ways:

- Via the DCS pin when operating in the external pin mode.
- Via register control by setting register *0x457*, bit[1], to 1.

Data Format Select. Data Format Select (DFS) can be used to select between offset binary or two's complement when operating in the external pin mode.

Output Enable (active-low, **OEB**). If the OEB pin is low, the output data drivers and output clock are enabled. If the OEB pin is high, the CMOS output data drivers and clock are placed in a high-impedance state; while the LVDS drivers are switched off. The OEB function is not intended for rapid access to a shared data bus.

External Reference Bias Resistor. The SD9251ET requires a 30k Ω , 1% resistor, between pin RBIAS and AGND to set the default bias current for the ADC.

Common-Mode Voltage. The VCM pin outputs the analog input common-mode bias voltage (VCM). This pin provides a stable DC reference that can be used to set the ADC input common-mode level, either directly through a passive network or indirectly as the common-mode reference for a driving amplifier. In typical applications, the default common-mode voltage is suitable and requires no adjustment. The common-mode voltage level is programmable through register *0xf11*, bits [4:3].

VREF The ADC supports both internal (default) and external voltage reference sources, selectable via the VREF pin. The selection between internal and external reference voltage can be made in one of two ways:

- Using the SENSE pin: a logic high level selects the external reference.
- Via register control: setting register *0x45d*, bits [5] and [12] to 1 selects the external reference.

Internal Reference Output. When the internal voltage reference is used, the VREF pin can function as a reference output. This output can be enabled by setting register *0x45d*, bits [14:13], to 0x3.

If the SENSE pin is held low, the reference output is enabled by default. To disable the reference output in this configuration, set register *0x45d*, bits [14:13], to 0x1.

The internal vref can be adjusted with *0x45d* bits [4:1]. Usually, the default value yields the optimal performance.

SERIAL PORT INTERFACE

The SD9251ET uses a 3-wire Serial Port Interface (SPI) that gives the user flexibility to configure the converter for specific functions, depending on the application, through a register space provided inside the ADC. The interface signals are:

- SCLK: defines the bit rate at which serial data is driven onto, and sampled from, the bus;
- CSB: defines the boundaries of a basic data 'unit', comprised of multiple serial bits;
- SDIO: is the serial data IO wire;

The read and write cycles are described in the figure below. The address space is 13 bits long ($A<12:0>$) and the data is 16 bits wide ($D<15:0>$). The complete instruction cycle is 32-bits long. The falling edge of CSB combines with the rising edge of SCLK marks the start of the instruction cycle. On a write transaction, the target register is updated on the falling edge of SCLK.

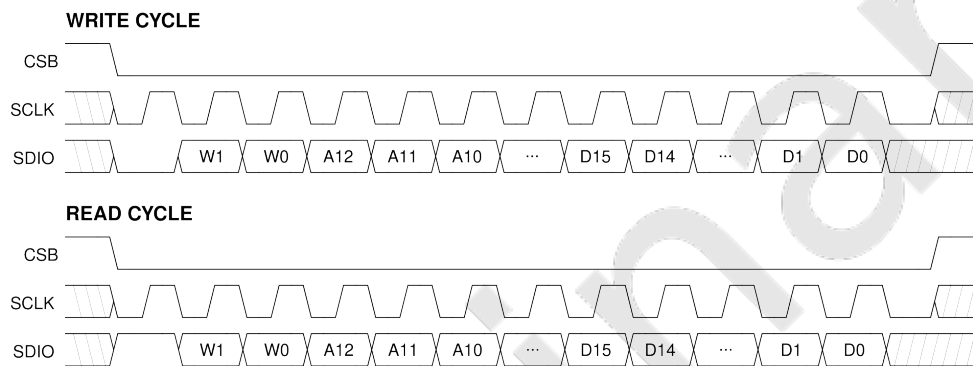


Figure 30: 3-wire SPI timing.

Table 20. SPI Timing.

| PARAMETER | TEMP | MIN | TYP | MAX | UNIT |
|--|------------------|-----|-----|-----|------|
| Setup time between the data and the rising edge of SCLK | t_{DS} | 2 | | | ns |
| Hold time between the data and the rising edge of SCLK | t_{HD} | 2 | | | ns |
| Period of the SCLK | t_{SCLK} | 40 | | | ns |
| Setup time between CSB and SCLK | $t_{S,CSB-SCLK}$ | 2 | | | ns |
| Hold time between CSB and SCLK | $t_{H,CSB-SCLK}$ | 2 | | | ns |
| Minimum period that SCLK should be in a logic high state | $t_{SCLK,high}$ | 10 | | | ns |
| Minimum period that SCLK should be in a logic low state | $t_{SCLK,low}$ | 10 | | | ns |
| Time from SCLK falling edge to SDIO switching from input to output | $t_{SDIO,EN}$ | 10 | | | ns |
| Time from SCLK falling edge to SDIO switching from output to input | $t_{SDIO,DIS}$ | 10 | | | ns |

Two bits, W1 and W0, determine how many bytes of data that can be transferred in the same write cycle (see Table 21). If more than 16 bits (2 Bytes) of data are being transferred the address is increased sequentially.

Table 21. SPI Word Length.

| [W1,W0] | Data length |
|---------|---------------------------------------|
| 00 | Not supported |
| 01 | Two bytes of data can be transferred |
| 10 | Not supported |
| 11 | Four bytes of data can be transferred |

The SPI pins should not be active when the full dynamic performance of the ADC is required. Noise from SCLK, CSB and the data transactions can degrade ADC performance.

Preliminary

OUTPUT MODE

Data Scrambler

Interference originating from the digital outputs of the ADC can be difficult to eliminate entirely. Such interference may result from capacitive or inductive coupling mechanisms, or from shared impedance paths in the ground plane. Even minimal coupling coefficients can introduce deterministic spurious tones into the ADC's output frequency spectrum. To mitigate this, digital output scrambling techniques can be employed prior to off-chip transmission. By randomizing the bit patterns, the spectral energy of these spurs is dispersed, effectively reducing their peak amplitudes and minimizing their impact on signal integrity.

The SD9251ET can apply an exclusive-OR logic operation between the LSB and all other data output bits, while the LSB, overflow and clock outputs are not affected.



When this function is used, the receiver must apply the same function to unscramble the received data.

The data scrambler is enabled by setting control register *0x4b5*, bit[13], to 1.

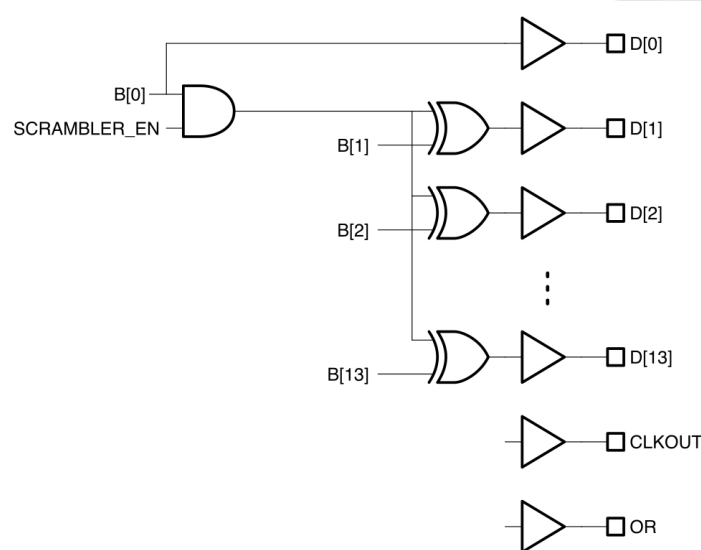


Figure 31: SD9251ET Data Scrambler.

Alternate Bit Polarity

The alternate bit polarity is particularly effective to suppress digital feedback and minimize noise coupling on the PCB when the ADC input signal is near mid-scale and of very small amplitude. In this case, the digital output tends to toggle between patterns dominated by either logic high or logic low states. This synchronized switching of multiple bits can induce significant transient currents in the ground plane, leading to increased digital noise. This mode, when activated, inverts all odd-numbered data output bits prior to the output buffer stage while even-numbered bits, along with the overflow and clock output, remain unaffected thus ensuring that approximately half of the output bits transition are high while the other half transition are low. This balanced switching behavior helps cancel out opposing current flows in the ground return path, thereby reducing overall ground noise. At the receiving end, the original data can be reconstructed by inverting the same odd-numbered bits. This mode operates independently of the digital output randomization feature, both functions can be enabled or disabled separately. The Alternate Bit Polarity mode is configured via serial programming of control register *0x4b5*, bit[14].

Output Test Modes

The output test options are described in Table 22 and are selected via SPI programming at register *0x4b5*, bits [5:2].

When an output test mode is enabled, the analog section of the ADC is disconnected from the digital back-end blocks and the test pattern is run through the output formatting block. These tests require an active input clock.

There are two pseudo-random number generators available, PN23 and PN9. The PN23 generator ($X^{23}+X^{18}+1$), selected by register $0x4b5$, bits [5:2], set to $0x5$, can be reset by setting register $0x4b5$, bit [12], low; while the PN9 generator (X^9+X^6+1), selected by register $0x4b5$ set to $0x6$, can be reset by setting register $0x4b5$, bit [11], low.

Table 22. Output Test Modes.

| Mode | Function |
|------|-----------------|
| 0 | Pass-Through |
| 1 | Midscale |
| 2 | +FS |
| 3 | -FS |
| 4 | Checkerboard |
| 5 | PN23 |
| 6 | PN9 |
| 7 | 1/0 word toggle |
| 8 | User input |
| 9 | 1/0 bit toggle |
| 10 | Unused |
| 11 | 1-bit high |
| 12 | Mixed frequency |
| 13 | Unused |
| 14 | Unused |
| 15 | Ramp |

Pass-through and test patterns 1, 2, 3, 5 and 6 are subject to output formatting, while the other test modes are not. Test patterns 1, 8 and 15 can be applied to either one channel or both channels using $0x4b5$, bit[7:6]. Patterns 4 and 7 can be toggled between the pattern and its inverse while test pattern 8 can be selected using registers $0x4bb$, $0x4bd$, $0x4bf$ and $0x4c1$.

CONTROL REGISTERS

This section describes the most commonly used control registers. For a description of the complete register map, refer to Appendix A: Register Map.

Each register is presented in the following format:

| Address: <HEX value> | | RW or RO | Default: <HEX value> |
|----------------------|---------------|--------------------|----------------------|
| bit field | default value | field description. | |

Notes

- **RW** = Read/Write
- **RO** = Read-Only
- For read-only registers, the default value is omitted.
- Registers not listed in these tables should not be written.



When updating control register values, always use a read-modify-write procedure. Some registers include reserved bit fields for internal engineering purposes. This approach ensures that these reserved bits remain unchanged and prevents unintended modifications.

CHIP TOP:

| Address: 0x457 | | RW | Default: 0x0015 |
|----------------|-----|----|--|
| [0] | 0x1 | | Duty Cycle Stabilizer enable (see [paragraph_DCS]). 0: Disable 1: Enable |
| [1] | 0x0 | | Duty Cycle Stabilizer on/off in SPI mode (see [paragraph_DCS]). 0: Off 1: On |
| [2] | 0x1 | | External output enable (OE/OEB) control (see [paragraph_OEB]). 0: Output Enabled 1: Output depends on pin OE/OEB |
| [3] | 0x0 | | Output disable (see [paragraph_OEB]). 0: Output depends on OE/OEB control and OE/OEB pin 1: Disabled |
| [6:4] | 0x1 | | Reserved. |
| [7] | 0x0 | | Software power down. 0: Active State 1: Power Down |
| [8] | 0x0 | | Software stand-by mode. 0: Active State 1: Stand-by Mode |

| Address: 0x463 | | RW | Default: 0x0019 |
|----------------|-----|----|--|
| [0] | 0x1 | | Enable clock receiver. 0: Disable 1: Enable |
| [4:1] | 0xc | | Reserved. |
| [7:5] | 0x0 | | Clock RX divider control. 0: Bypass 1: Divide by 2 2: Divide by 3 3: Divide by 4 4: Divide by 5 5: Divide by 6 6: Divide by 7 7: Divide by 8 |
| [8] | 0x0 | | Enable on-chip 100Ohm termination. 0: Disable 1: Enable |
| [9] | 0x0 | | Clock polarity control when DCS is enabled. 0: Disable 1: Invert |
| [10] | 0x0 | | Enable SYNC pin synchronization. 0: Disable 1: Enable |

| Address: 0x465 | | RW | Default: 0x0001 |
|----------------|-----|----|--|
| [2:0] | 0x1 | | Output data interleaver. 0: pass through, no interleaving 1: pass through, channels swapped, no interleaving 2: N/A 3: N/A 4: parallel ADC_A/ADC_B interleaving 5: parallel ADC_B/ADC_A interleaving 6: even-odd interleaving 7: odd-even interleaving |

| Address: 0x473 | | RW | Default: 0x0000 |
|----------------|-----|----|--|
| [4:0] | 0x0 | | Reserved. |
| [9:5] | 0x0 | | Output data delay in parallel CMOS mode. The output data delay is increased by 250ps * (register value) with respect to the clock |
| [13:10] | 0x0 | | Reserved. |
| [14] | 0x0 | | Output data sending clock polarity in parallel CMOS mode. 0: Not inverted 1: Inverted |
| [13:10] | 0x0 | | Output clock delay. The output clock delay is increased by 250ps * (register value) with respect to the data |
| [14] | 0x0 | | Output clock polarity. 0: Not inverted 1: Inverted |

| Address: 0x4b5 | | RW | Default: 0x18c0 |
|----------------|-----|----|---|
| [1:0] | 0x0 | | Output format. 0: Offset binary 1: Two's complement 2: Gray code 3: Offset binary |
| [5:2] | 0x0 | | Output test mode select (see Table 22). |
| [6] | 0x1 | | Output test channel CH. A 0: Disable 1: Enable |
| [7] | 0x1 | | Output test channel CH. B 0: Disable 1: Enable |
| [8] | 0x0 | | Output test toggle mode. Toggle between user test pattern 0 and 1. |
| [10:9] | 0x0 | | Reserved. |
| [11] | 0x1 | | PN9 generator reset (active low). |
| [12] | 0x1 | | PN23 generator reset (active low). |
| [13] | 0x0 | | Enable the output data scrambler. 0: Disable 1: Enable |
| [14] | 0x0 | | Enable alternate bit polarity switch. 0: Disable 1: Enable |

ADC A:

| Address: 0xdc1 | | RW | Default: 0xbfff |
|----------------|-------|----|--------------------------------------|
| [3:0] | 0xf | | Reserved. |
| [4] | 0x1 | | Calibration soft reset (active low). |
| [15:5] | 0x5f9 | | Reserved. |

See Table 19 for valid configurations for the following registers:

| Address: 0xdcd | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg1 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg1 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xdd5 | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg2 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg2 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xddd | | RW | Default: 0x16c3 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg3 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0xd8 | | Reserved. |
| [13:12] | 0x1 | | Stg3 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xde1 | | RW | Default: 0xbbe8 |
|----------------|------|----|--|
| [7:0] | 0xe8 | | Time allocated for calibration (see Table 19). |
| [8] | 0x1 | | Enable calibration (see Table 19). |
| [9] | 0x1 | | Enable foreground calibration (see Table 19). |
| [10] | 0x0 | | Reserved. |
| [11] | 0x1 | | Enable stg1 calibration (see Table 19). |
| [12] | 0x1 | | Enable stg2 calibration (see Table 19). |
| [13] | 0x1 | | Enable stg3 calibration (see Table 19). |
| [14] | 0x0 | | Background calibration parallel mode (see Table 19). |
| [15] | 0x1 | | Disable background calibration mode for all stages (see Table 19). |

ADC B:

| Address: 0xcc1 | | RW | Default: 0xbfff |
|----------------|-------|----|--------------------------------------|
| [3:0] | 0xf | | Reserved. |
| [4] | 0x1 | | Calibration soft reset (active low). |
| [15:5] | 0x5f9 | | Reserved. |

See Table 19 for valid configurations for the following registers:

| Address: 0xccd | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg1 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg1 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xcd5 | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg2 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg2 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xcd8 | | RW | Default: 0x16c3 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg3 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0xd8 | | Reserved. |
| [13:12] | 0x1 | | Stg3 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xce1 | | RW | Default: 0xbbe8 |
|----------------|------|----|--|
| [7:0] | 0xe8 | | Time allocated for calibration (see Table 19). |
| [8] | 0x1 | | Enable calibration (see Table 19). |
| [9] | 0x1 | | Enable foreground calibration (see Table 19). |
| [10] | 0x0 | | Reserved. |
| [11] | 0x1 | | Enable stg1 calibration (see Table 19). |
| [12] | 0x1 | | Enable stg2 calibration (see Table 19). |
| [13] | 0x1 | | Enable stg3 calibration (see Table 19). |
| [14] | 0x0 | | Background calibration parallel mode (see Table 19). |
| [15] | 0x1 | | Disable background calibration mode for all stages (see Table 19). |

ADC BRING-UP

The SD9251ET does not require a specific power-up sequence; however, it is recommended to apply the DRVDD first followed by the AVDD.

Extended Temperature

To maintain full ADC performance over the extended temperature range, background calibration must be enabled. The registers in Table 23 must be programmed via the SPI interface:

Table 23. Background Calibration Enable.

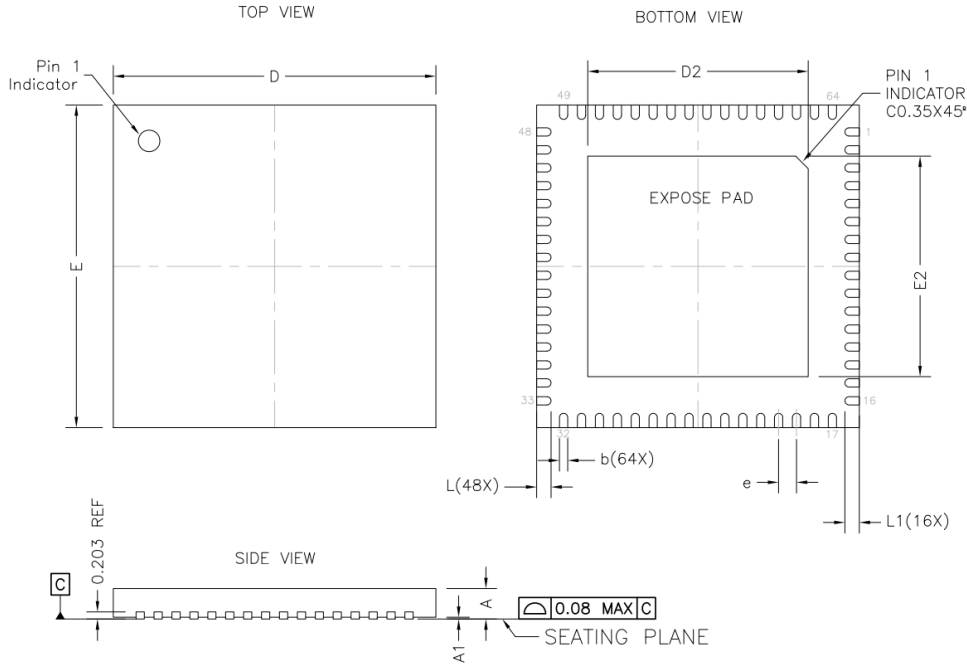
| Register Address | Value |
|------------------|--------|
| 0xdcf | 0xd80 |
| 0xccf | 0xd80 |
| 0xde1 | 0xfb80 |
| 0xce1 | 0xfb80 |
| 0xde3 | 0x0 |
| 0xce3 | 0x0 |
| 0x809 | 0x18d4 |
| 0x80b | 0x18d4 |

ORDERING INFORMATION

This product is protected by several U.S. Patents (www.silannasemi.com/patents).

Preliminary

PACKAGE DRAWING



| DIMENSION TABLE | | | |
|-----------------|----------|---------|---------|
| SYMBOL | MINIMUM | NOMINAL | MAXIMUM |
| A | 0.70 | 0.75 | 0.80 |
| A1 | 0.00 | 0.02 | 0.05 |
| b | 0.20 | 0.25 | 0.30 |
| D | 8.90 | 9.00 | 9.10 |
| D2 | 6.10 | 6.15 | 6.20 |
| E | 8.90 | 9.00 | 9.10 |
| E2 | 6.10 | 6.15 | 6.20 |
| e | 0.50 BSC | | |
| L | 0.35 | 0.40 | 0.45 |
| L1 | 0.33 | 0.38 | 0.43 |

- NOTE:
1. Dimensioning and tolerancing conform to ASME Y14.5-2009
 2. All dimensions are in millimeters
 3. N is the total number of terminals
 4. Unilateral coplanarity zone applies to the exposed pas as well as the terminals
 5. Lead Finish: 100% Sn

Figure 32: Package Dimensions.

APPENDIX A: Register Map

This section provides a comprehensive description of the complete register map, detailing all available control and status registers within the device.

0x400 - CHIP_TOP

| Address: 0x455 | | RW | Default: 0x0001 |
|----------------|-----|----|--------------------------|
| [0] | 0x1 | | Soft reset (active low). |

| Address: 0x457 | | RW | Default: 0x0015 |
|----------------|-----|----|--|
| [0] | 0x1 | | Duty Cycle Stabilizer enable (see [paragraph_DCS]). 0: Disable 1: Enable |
| [1] | 0x0 | | Duty Cycle Stabilizer on/off in SPI mode (see [paragraph_DCS]). 0: Off 1: On |
| [2] | 0x1 | | External output enable (OE/OEB) control (see [paragraph_OEB]). 0: Output Enabled 1: Output depends on pin OE/OEB |
| [3] | 0x0 | | Output disable (see [paragraph_OEB]). 0: Output depends on OE/OEB control and OE/OEB pin 1: Disabled |
| [6:4] | 0x1 | | Reserved. |
| [7] | 0x0 | | Software power down. 0: Active State 1: Power Down |
| [8] | 0x0 | | Software stand-by mode. 0: Active State 1: Stand-by Mode |

| Address: 0x45d | | RW | Default: 0x0095 |
|----------------|-----|----|---|
| [0] | 0x1 | | ADC reference voltage enable. 0: Disabled 1: Enabled |
| [4:1] | 0xa | | ADC reference voltage value. 0: Lowest ... 15: Highest |
| [5] | 0x0 | | Set reference. 0: Internal 1: External from VREF pin |
| [11:6] | 0x2 | | Reserved. |
| [12] | 0x0 | | Enable selection between Internal and External VREF selection via bit 5. 0: Bit [5] selection disabled 1: Bit [5] selection enabled |
| [13] | 0x0 | | Enable selection of VREF out via bit 14. 0: Bit [14] selection disabled 1: Bit [14] selection enabled |
| [14] | 0x0 | | Enable VREF pin as reference voltage output. 0: Disabled 1: Enabled |

| Address: 0x463 | | RW | Default: 0x0019 |
|----------------|-----|----|--|
| [0] | 0x1 | | Enable clock receiver. 0: Disable 1: Enable |
| [4:1] | 0xc | | Reserved. |
| [7:5] | 0x0 | | Clock RX divider control. 0: Bypass 1: Divide by 2 2: Divide by 3 3: Divide by 4 4: Divide by 5 5: Divide by 6 6: Divide by 7 7: Divide by 8 |
| [8] | 0x0 | | Enable on-chip 100Ohm termination. 0: Disable 1: Enable |
| [9] | 0x0 | | Clock polarity control when DCS is enabled. 0: Disable 1: Invert |
| [10] | 0x0 | | Enable SYNC pin synchronization. 0: Disable 1: Enable |

| Address: 0x465 | | RW | Default: 0x0001 |
|----------------|-----|----|--|
| [2:0] | 0x1 | | Output data interleaver. 0: pass through, no interleaving 1: pass through, channels swapped, no interleaving 2: N/A 3: N/A 4: parallel ADC_A/ADC_B interleaving 5: parallel ADC_B/ADC_A interleaving 6: even-odd interleaving 7: odd-even interleaving |

| Address: 0x467 | | RW | Default: 0x3850 |
|----------------|------|----|--|
| [0] | 0x0 | | LVDS enable. 0: Disable 1: Enable |
| [1] | 0x0 | | LVDS reduced swing mode. 0: Disable 1: Enable |
| [10:2] | 0x14 | | Reserved. |
| [13:11] | 0x7 | | LVDS amplitude. 0: Smallest amplitude 0: ... 7: Largest amplitude |
| [15:14] | 0x0 | | Reserved. |

| Address: 0x473 | | RW | Default: 0x0000 |
|----------------|-----|--|-----------------|
| [4:0] | 0x0 | Reserved. | |
| [9:5] | 0x0 | Output data delay in parallel CMOS mode. The output data delay is increased by 250ps * (register value) with respect to the clock | |
| [13:10] | 0x0 | Reserved. | |
| [14] | 0x0 | Output data sending clock polarity in parallel CMOS mode. 0: Not inverted 1: Inverted | |
| [13:10] | 0x0 | Output clock delay. The output clock delay is increased by 250ps * (register value) with respect to the data | |
| [14] | 0x0 | Output clock polarity. 0: Not inverted 1: Inverted | |

| Address: 0x475 | | RW | Default: 0x0001 |
|----------------|-----|--|-----------------|
| [0] | 0x1 | Enable VCM. 0: Disable 1: Enable | |

| Address: 0x4b5 | | RW | Default: 0x18c0 |
|----------------|-----|---|-----------------|
| [1:0] | 0x0 | Output format. 0: Offset binary 1: Two's complement 2: Gray code 3: Offset binary | |
| [5:2] | 0x0 | Output test mode select (see Table 22). | |
| [6] | 0x1 | Output test channel CH. A 0: Disable 1: Enable | |
| [7] | 0x1 | Output test channel CH. B 0: Disable 1: Enable | |
| [8] | 0x0 | Output test toggle mode. Toggle between user test pattern 0 and 1. | |
| [10:9] | 0x0 | Reserved. | |
| [11] | 0x1 | PN9 generator reset (active low). | |
| [12] | 0x1 | PN23 generator reset (active low). | |
| [13] | 0x0 | Enable the output data scrambler. 0: Disable 1: Enable | |
| [14] | 0x0 | Enable alternate bit polarity switch. 0: Disable 1: Enable | |

| Address: 0x4b7 | | RW | Default: 0x0092 |
|----------------|--------|-------------------|-----------------|
| [15:0] | 0x0092 | PN9 initial seed. | |

| Address: 0x4b9 | | RW | Default: 0x3aff |
|----------------|--------|--------------------|-----------------|
| [15:0] | 0x3aff | PN23 initial seed. | |

| Address: 0x4bb | | RW | Default: 0x0000 |
|----------------|--------|--|-----------------|
| [15:0] | 0x0000 | User test pattern 0 (CH. A). | |
| Address: 0x4bd | | RW | Default: 0x0000 |
| [15:0] | 0x0000 | User test pattern 1 (CH. A). | |
| Address: 0x4bf | | RW | Default: 0x0000 |
| [15:0] | 0x0000 | User test pattern 0 (CH. B). | |
| Address: 0x4c1 | | RW | Default: 0x0000 |
| [15:0] | 0x0000 | User test pattern 1 (CH. B). | |
| Address: 0x4c9 | | RW | Default: 0x0000 |
| [0] | 0x0 | Disable auto-recalibration. 0: Disable 1: Enable | |
| [15:1] | 0x0 | Reserved. | |
| Address: 0x4cf | | RW | Default: 0x0035 |
| [14:0] | 0x35 | Reserved. | |
| [15] | 0x0 | Disable production test mode. 0: Test mode enabled 1: Test mode disabled | |
| Address: 0x4d3 | | RW | Default: 0x0007 |
| [3:0] | 0x7 | LVDS common mode voltage. | |
| [7:4] | 0x0 | Reserved. | |
| Address: 0x4fd | | RO | Default: N/A |
| [2:0] | | Chip revision. | |
| [6:3] | | Label ID. | |
| [8:7] | | Reserved. | |
| [10:9] | | Resolution ID for device 0: 10-bit 1: 12-bit 2: 14-bit 3: 16-bit | |
| [13:11] | | Speed ID for device. | |

| Address: 0x4ff | RO | Default: N/A |
|----------------|----|--|
| [0] | | Reserved. |
| [1] | | Analog Supply Ready. 0: Not ready 1: Ready |
| [2] | | Digital Supply Ready. |
| [3] | | I/O Supply Ready. 0: Not ready 1: Ready |
| [4] | | Sense pin status. |
| [5] | | SPI enabled. 0: Not enabled 1: Enabled |
| [6] | | Power down pin status. 0: Inactive 1: Active |
| [9:7] | | Reserved. |

0xF00 - ADC_DUAL

| Address: 0x809 | RW | Default: 0x1800 |
|----------------|-------|---|
| [11:0] | 0x800 | ADC A channel gain. 0x000: 0.0 0x800: 1.0 0xfff: 2.0 |
| [12] | 0x1 | Enable ADC A path gain and offset. |

| Address: 0x80b | RW | Default: 0x1800 |
|----------------|-------|---|
| [11:0] | 0x800 | ADC B channel gain. 0x000: 0.0 0x800: 1.0 0xfff: 2.0 |
| [12] | 0x1 | Enable ADC B path gain and offset. |

| Address: 0x80d | RW | Default: 0x0000 |
|----------------|--------|--|
| [15:0] | 0x0000 | ADC A channel offset. Signed 16-bit two's complement number. |

| Address: 0x80f | RW | Default: 0x0000 |
|----------------|--------|--|
| [15:0] | 0x0000 | ADC B channel offset. Signed 16-bit two's complement number. |

| Address: 0xf03 | | RW | Default: 0x07f9 |
|----------------|------|----|---|
| [0] | 0x1 | | Enable top level bias. 0: Disable 1: Enable |
| [2:1] | 0x0 | | Reserved. |
| [3] | 0x1 | | ADC_B enable. 0: Disable 1: Enable |
| [4] | 0x1 | | ADC_A enable. 0: Disable 1: Enable |
| [10:5] | 0x3f | | Mask for enable pin. |

| Address: 0xf05 | | RW | Default: 0x0030 |
|----------------|------|----|--|
| [5:0] | 0x30 | | Mask for stand-by pin. |
| [6] | 0x0 | | Stand-by ADC_B. 0: Disable 1: Enable |
| [7] | 0x0 | | Stand-by ADC_A. 0: Disable 1: Enable |

| Address: 0xf07 | | RW | Default: 0x0043 |
|----------------|-----|----|--|
| [0] | 0x1 | | Digital clock enable. 0: Disable 1: Enable |
| [1] | 0x1 | | Analog clock enable. 0: Disable 1: Enable |
| [2] | 0x0 | | Reserved. |
| [3] | 0x0 | | Clock source select. 0: ADC_B 1: ADC_A |
| [5:4] | 0x0 | | Reserved. |
| [6] | 0x1 | | ADC clock generator reset (active low). |
| [7] | 0x0 | | Reserved. |

| Address: 0xf11 | | RW | Default: 0x000b |
|----------------|-----|----|--|
| [2:0] | 0x3 | | Reserved. |
| [4:3] | 0x1 | | VCM voltage control. 0: Lowest common-mode voltage ... 3: Highest common-mode voltage |

0xDC0 - ADC A

| Address: 0xdc1 | | RW | Default: 0xbfff |
|----------------|-------|----|--------------------------------------|
| [3:0] | 0xf | | Reserved. |
| [4] | 0x1 | | Calibration soft reset (active low). |
| [15:5] | 0x5f9 | | Reserved. |

| Address: 0xdc9 | | RW | Default: 0x06a5 |
|----------------|------|----|------------------------------|
| [8:0] | 0xa5 | | Reserved. |
| [9] | 0x1 | | Stg1 enable background mode. |
| [11:10] | 0x1 | | Reserved. |

| Address: 0xdcd | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg1 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg1 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xdcf | | RW | Default: 0x0d85 |
|----------------|-------|----|---|
| [2:0] | 0x5 | | Stg1 calibration convergence speed in background mode (see Table 19). |
| [11:3] | 0x1b0 | | Reserved. |

| Address: 0xdd1 | | RW | Default: 0x02a5 |
|----------------|------|----|--|
| [0] | 0x1 | | Stage 2 gain error calibration enable. |
| [1] | 0x0 | | Stage 2 gain error calibration only. |
| [8:2] | 0x29 | | Reserved. |
| [9] | 0x1 | | Stg2 enable background mode. |
| [11:10] | 0x0 | | Reserved. |

| Address: 0xdd3 | | RW | Default: 0x0bc0 |
|----------------|-----|----|------------------------------------|
| [0] | 0x0 | | Stg2 force calibration data. |
| [3:1] | 0x0 | | Stg2 calibration data register. |
| [6:4] | 0x4 | | Stg2 bg calibration data register. |
| [9:7] | 0x7 | | Stg2 fg calibration data register. |
| [11:10] | 0x2 | | Stg2 calibration mode. |
| [14:12] | 0x0 | | Stg2 capacitor select register. |
| [15] | 0x0 | | Stg2 cal data magnitude. |

| Address: 0xdd5 | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg2 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg2 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xdd7 | | RW | Default: 0x0001 |
|----------------|-----|----|---|
| [2:0] | 0x1 | | Stg2 calibration convergence speed in background mode (see Table 19). |
| [11:3] | 0x0 | | Reserved. |

| Address: 0xddd | | RW | Default: 0x16c3 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg3 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0xd8 | | Reserved. |
| [13:12] | 0x1 | | Stg3 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xde1 | | RW | Default: 0xbbe8 |
|----------------|------|----|--|
| [7:0] | 0xe8 | | Time allocated for calibration (see Table 19). |
| [8] | 0x1 | | Enable calibration (see Table 19). |
| [9] | 0x1 | | Enable foreground calibration (see Table 19). |
| [10] | 0x0 | | Reserved. |
| [11] | 0x1 | | Enable stg1 calibration (see Table 19). |
| [12] | 0x1 | | Enable stg2 calibration (see Table 19). |
| [13] | 0x1 | | Enable stg3 calibration (see Table 19). |
| [14] | 0x0 | | Background calibration parallel mode (see Table 19). |
| [15] | 0x1 | | Disable background calibration mode for all stages (see Table 19). |

| Address: 0xde3 | | RW | Default: 0x0008 |
|----------------|-----|----|--|
| [2:0] | 0x0 | | Reserved. |
| [3] | 0x1 | | Clipping control to reserve some headroom for background calibration signals (active low). |

| Address: 0xdeb | | RW | Default: 0x0000 |
|----------------|-----|----|---|
| [0] | 0x0 | | Calibration status. 0: Not done 1: Done |
| [7:1] | 0x0 | | Reserved. |

| Address: 0xdef | | RO | Default: N/A |
|----------------|--|----|-----------------------|
| [0] | | | Calibration complete. |
| [15:1] | | | Reserved. |

0xCC1 - ADC B

| Address: 0xcc1 | | RW | Default: 0xbfff |
|----------------|-------|----|--------------------------------------|
| [3:0] | 0xf | | Reserved. |
| [4] | 0x1 | | Calibration soft reset (active low). |
| [15:5] | 0x5f9 | | Reserved. |

| Address: 0xcc9 | | RW | Default: 0x06a5 |
|----------------|------|----|------------------------------|
| [8:0] | 0xa5 | | Reserved. |
| [9] | 0x1 | | Stg1 enable background mode. |
| [11:10] | 0x1 | | Reserved. |

| Address: 0xccd | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg1 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg1 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xccf | | RW | Default: 0x0d85 |
|----------------|-------|----|---|
| [2:0] | 0x5 | | Stg1 calibration convergence speed in background mode (see Table 19). |
| [11:3] | 0x1b0 | | Reserved. |

| Address: 0xcd1 | | RW | Default: 0x02a5 |
|----------------|------|----|--|
| [0] | 0x1 | | Stage 2 gain error calibration enable. |
| [1] | 0x0 | | Stage 2 gain error calibration only. |
| [8:2] | 0x29 | | Reserved. |
| [9] | 0x1 | | Stg2 enable background mode. |
| [11:10] | 0x0 | | Reserved. |

| Address: 0xcd5 | | RW | Default: 0x1483 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg2 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0x90 | | Reserved. |
| [13:12] | 0x1 | | Stg2 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xcd7 | | RW | Default: 0x0001 |
|----------------|-----|----|---|
| [2:0] | 0x1 | | Stg2 calibration convergence speed in background mode (see Table 19). |
| [11:3] | 0x0 | | Reserved. |

| Address: 0xcdd | | RW | Default: 0x16c3 |
|----------------|------|----|--|
| [2:0] | 0x3 | | Stg3 calibration convergence speed in foreground mode (see Table 19). |
| [11:3] | 0xd8 | | Reserved. |
| [13:12] | 0x1 | | Stg3 calibration randomization sequence in foreground mode (see Table 19). |

| Address: 0xce1 | | RW | Default: 0xbbe8 |
|----------------|------|----|--|
| [7:0] | 0xe8 | | Time allocated for calibration (see Table 19). |
| [8] | 0x1 | | Enable calibration (see Table 19). |
| [9] | 0x1 | | Enable foreground calibration (see Table 19). |
| [10] | 0x0 | | Reserved. |
| [11] | 0x1 | | Enable stg1 calibration (see Table 19). |
| [12] | 0x1 | | Enable stg2 calibration (see Table 19). |
| [13] | 0x1 | | Enable stg3 calibration (see Table 19). |
| [14] | 0x0 | | Background calibration parallel mode (see Table 19). |
| [15] | 0x1 | | Disable background calibration mode for all stages (see Table 19). |

| Address: 0xce3 | | RW | Default: 0x0008 |
|----------------|-----|----|--|
| [2:0] | 0x0 | | Reserved. |
| [3] | 0x1 | | Clipping control to reserve some headroom for background calibration signals (active low). |

| Address: 0xceb | | RW | Default: 0x0000 |
|----------------|-----|----|---|
| [0] | 0x0 | | Calibration status. 0: Not done 1: Done |
| [7:1] | 0x0 | | Reserved. |

| Address: 0xcef | | RO | Default: N/A |
|----------------|--|----|-----------------------|
| [0] | | | Calibration complete. |
| [15:1] | | | Reserved. |

REVISION HISTORY

| Version | Date | Comment |
|---------|------------------|------------------|
| 1.0 | January 20, 2026 | Initial Release. |

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Preliminary